

Creating Robust Designs

Summary: Engineering products, from concrete structures to electronic circuits, are designed to perform a function by selecting component part parameters which will permit successful operation of the product in an expected use environment. Variations in the part parameters or in the operating environment will usually degrade the desired performance. Figure 1 shows that variation in the strength of a part and variation in the stress it sees can result in an area of overlap in which the stress can be greater than the strength, resulting in a failure. Since variations cannot be avoided, a number of countermeasures have been devised to assure satisfactory operation of a product when conditions deviate from nominal. Although some particular countermeasures claim the title "robust design" (indeed, the term is a registered trademark of the American Supplier Institute), all methods of dealing with variations can help to produce robust designs in the generic meaning of the term.

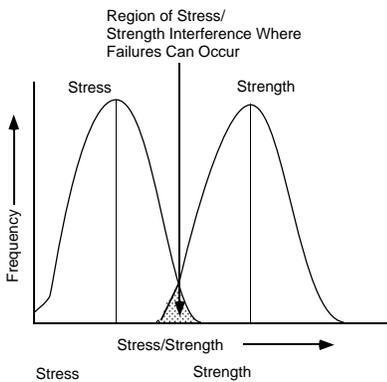


Figure 1

In this START sheet, we will briefly describe the most common countermeasures to variability: safety factors/derating, worst case circuit analysis, the "six sigma" design philosophy, process control based on the statistical design of experiments, and some contributions of Genichi Taguchi.

Safety Factors/Derating: These terms refer to the limiting of the nominal stresses on all parts to levels below their specified maximum. The use of safety factors in structures is common (e.g., a column meant to support a five ton load might be designed for ten tons). Similar policies in electronics engineering (e.g., a power transistor rated at 25 watts may be operated at 20 watts) are called derating. The effect is to shift the stress curve in Figure 1 to the left, reducing the area of stress-strength overlap. Critical parameters will differ from part to part (e.g., wattage for a power transistor vs. voltage for a capacitor) and some parts should not be derated (e.g., aluminum electrolytic capacitors). Derating guidelines are tabulated

in the *Reliability Toolkit: Commercial Practice Edition*, available from RAC and also in MIL-STD-975K, Notice 2, *NASA Standard Parts Derating*, the Rome Laboratory Technical Report RL-TR-92-11, *Advanced Technology Component Derating*, and the Naval Sea Systems Command TE000-AB-GTP-010, *Parts Derating Requirements and Application Manual*. Structural safety factors are recommended in civil and mechanical engineering handbooks and prescribed in building codes.

Worst Case Analysis: Worst Case Analysis and the electronic specific Worst Case Circuit Analysis (WCCA) consider the impact on desired performance of expected variations in part parameters. For example, a WCCA could determine whether or not the frequency of a radar transmitter would be within specifications if the parameters of parts used were at unfavorable "off-nominal" values. The most conservative worst case analysis calculates product performance with all parts at their worst value and causing errors in the same direction. This is known as extreme value analysis and is the easiest approach. Other approaches are root-sum-squared and Monte Carlo analysis which consider the statistical distribution of variables, recognizing that random variations of different parts are rarely all at extreme values in the same direction and that one variation can offset another. These more realistic approaches are more difficult to perform, but are important when the penalties of designing for the extreme value are too severe to make it practical. In any event, parts are selected so that their expected variations do not preclude acceptable product operation, as determined by the method used. WCCA is discussed in the *Reliability Toolkit: Commercial Practices Edition*. More detailed treatment may be found in the RAC publication, *Worst Case Circuit Analysis Application Guidelines*. Finite element analysis (FEA) is a computer technique invented for analyzing stresses in mechanical and structural assemblies (and now also widely used in electronic stress analysis).

"Six Sigma" Design: The impact of variation in a product can be determined by comparing the distribution of the parameter of interest with the specified limits to that parameter. One measure of variation is the population standard deviation (sigma), which is estimated from samples using the formula:

$$\sigma = \sqrt{\frac{\sum_{i=1}^n (X_i - \bar{X})^2}{n-1}}$$

Eq. 1

- σ = population standard deviation
- X_i = value of sample (i)
- \bar{X} = mean of sample values
- n = number of samples

Using the standard deviation, one can then determine the proportion of the product which will be between the upper and lower specified limits, and thus considered acceptable. For example, if a parameter is distributed normally, 66.3% of the product will have a parameter value within plus and minus one standard deviation of the mean value of the parameter, 95.5% will measure between plus and minus two, and 99.7% will be between plus and minus three sigmas from the mean. Figure 2 illustrates this.

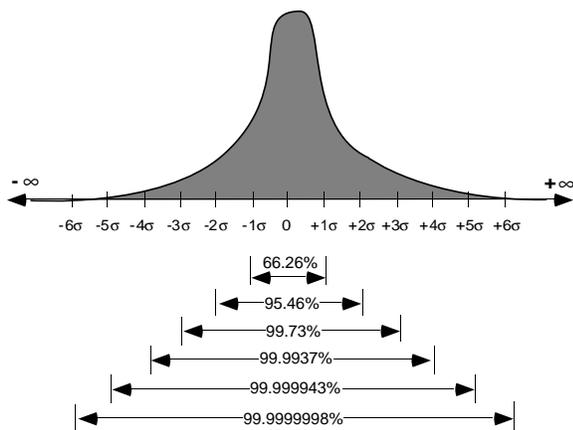


Figure 2

Comparing the specification limits to the variation in the product yields a measure of robustness. One of these measures is Process Capability, which is calculated by Equation 2. A Process Capability of 1.0 means that 99.7% of the product will be “in-spec.” Anything lower is

generally considered bad, and quality oriented companies aim at higher values.

$$Cp = \frac{USL - LSL}{6\sigma}$$

Eq. 2

- USL = Upper specification limit
- LSL = Lower specification limit
- σ = Standard deviation

One shortcoming of the Process Capability measure is that it presumes the mean of the parameter of interest in the product will be its target value, as illustrated in Figure 3. However, “real world” distributions are more likely to resemble Figure 4, where the product mean value is displaced from the target. For this reason, a measure called Process Performance, Equation 3, is often preferred.

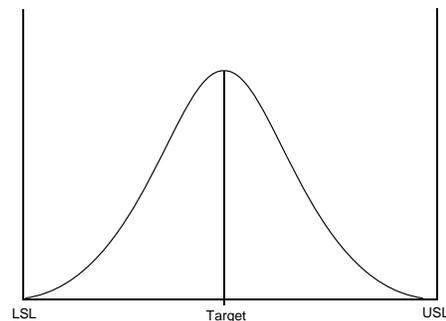


Figure 3

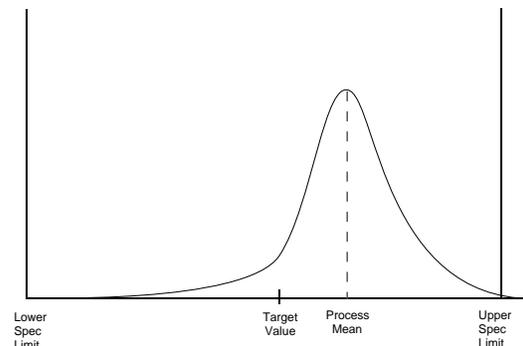


Figure 4

About the Reliability Analysis Center

The Reliability Analysis Center is a Department of Defense Information Analysis Center (IAC). RAC serves as a government and industry focal point for efforts to improve the reliability, maintainability and quality of manufactured components and systems. To this end, RAC collects, analyzes, archives in computerized databases, and publishes data concerning the quality and reliability of equipments and systems, as well as the microcircuit, discrete semiconductor, and electromechanical and mechanical components that comprise them. RAC also evaluates and publishes information on engineering techniques and methods. Information is distributed through data compilations, application guides, data products and programs on computer media, public and private training courses, and consulting services.

Located in Rome, NY, the Reliability Analysis Center is sponsored by the Defense Technical Information Center (DTIC). Since its inception in 1968, the RAC has been operated by IIT Research Institute (IITRI). Technical management of the RAC is provided by the U.S. Air Force’s Rome Laboratory (formerly Rome Air Development Center).

$$Cpk = \frac{\text{Min}\{(USL - \mu); (\mu - LSL)\}}{3\sigma} \quad \text{Eq. 3}$$

- Min{a;b} = Smaller of the two values
- USL, LSL, σ = As above
- μ = Process mean

The “Six Sigma” program formulated by Motorola aims for such low variability in the product that six sigmas will fit between the specification limits (i.e., a Process Capability of 2.0), which, presuming the mean of the product is 1.5 sigmas off target (i.e., a Process Performance of 1.5), translates to 3.4 items per million out of specified limits. By way of comparison, the average business process is a “four sigma” process which translates to 6,200 items per million “out of spec.” Achieving a “six sigma” process requires the control of critical process parameters, which can be identified by the statistical design of experiments, the next topic.

Statistical Design of Experiments (DOE): DOE is a systematic approach to determining the optimum settings of process parameters. Parameters deemed to be important (usually by an *ad hoc* team of experts) are varied and the results observed. The simplest form is an experiment in which a high and low value is picked for each parameter and every possible combination is used. For example, a team trying to improve a wave-solder process might suggest varying the temperature, length of exposure and lead/tin ratio of the solder to determine ways to reduce solder defects. A high and low value is selected for each parameter. Every possible combination of high and low values is tested and its effect on solder defects measured. Adding for illustration a test at nominal conditions (i.e. those used before the experiment) the results of such an experiment might be as shown in Table 1.

Table 1

Test	Temp	Length	L/T Ratio	Defect Rate
1	N	N	N	1.5
2	L	L	L	3.2
3	H	L	L	3.1
4	L	H	L	1.9
5	H	H	L	2.4
6	L	L	H	1.6
7	H	L	H	1.6
8	L	H	H	3.3
9	H	H	H	2.2

Table 1 shows that the nominal settings also seem to be the optimal settings. However, we have not discussed other factors that may affect solder defects. These may be factors not under the control of the process owner, and before he accepts the nominal conditions as best, he should examine the robustness of all the settings under

varying outside factors. For example, he may get boards of different sizes to solder. Do his test results on one board size hold for other sizes? Does the number of layers in the board make a difference? In our next topic, we shall discuss some methods championed by Genichi Taguchi, which answer such questions. It should be noted that there are various other means for considering robustness, such as randomizing the order of the experiment and repeating it several times, to average out the impact of unknown factors not tested.

It should also be noted that off-on factors, like the presence or absence of a flux in the solder, can be handled by calling the presence of the flux a high setting and the absence, a low setting (or vice-versa). Also, there are tests using more than two settings for some or all factors and fractional factorial test plans that provide more economical testing at the cost of not observing all possible interactions of the factors.

A beginning text on DOE is *Understanding Industrial Designed Experiments*, by Schmidt and Launsby, published in 1989 by the Air University Press, Colorado Springs.

Taguchi Innovations: Genichi Taguchi is a noted champion of reducing variation through DOE. Some of his innovations are the testing of “noise” arrays and the use of “signal to noise” ratios to determine optimum settings for robustness.

For example, a Taguchi approach to the experiment described in Table 1 might have extended it to include an “inner array” of the controllable factors tested and an “outer array” of uncontrollable (“noise”) factors such as board size and number of layers. Assuming a high and low value were determined for each of these factors and including the results of Table 1 as a nominal setting for these factors, we might obtain the results shown in Table 2.

Table 2

Test	Controllable Variations			Uncontrolled Variations					
	Temp.	Length	L/T ratio	Size:	N	L	H	L	H
				Layers:	N	L	L	H	H
1	N	N	N	1.5	2.9	1.9	2.4	2.6	
2	L	L	L	3.2	9.0	1.8	1.6	7.8	
3	H	L	L	3.1	2.6	2.0	2.3	4.8	
4	L	H	L	1.9	2.7	2.0	1.5	3.4	
5	H	H	L	2.4	2.2	1.5	1.7	1.9	
6	L	L	H	1.6	2.4	1.6	1.5	2.9	
7	H	L	H	1.6	1.9	1.7	1.7	1.8	
8	L	H	H	3.3	3.3	1.6	1.6	3.3	
9	H	H	H	2.2	2.6	1.8	1.6	1.9	

The optimum solution shown in Table 1 does not appear best in Table 2. The settings of the controllable factors for

other tests (e.g., 5, 6 and 7) give better results across the spectrum of the uncontrolled variations (i.e., more robustness).

Another Taguchi technique is to measure the experiment results in terms which consider both the measured values and their variations. These are called "signal to noise" ratios and stem from another Taguchi invention, called "loss functions." There are loss functions for "smaller is better" (e.g., defects), "nominal is better" (e.g., dimensions of a mechanical part), and "larger is better" (e.g., tensile strength). Each assumes that loss increases with the square of the distance a parameter is from its target value. For the example we have been using, the signal to noise ratio based on the "smaller is better" loss function is:

$$S/N = -10 \text{ Log } \left(\frac{1}{n} \sum Y_i^2 \right) \quad \text{Eq. 4}$$

n = Number of results
 Y_i = Value of one result

Combining the experimental results shown in Table 2 into signal to noise ratios, yields Table 3, which indicates that the settings of test number 7 create the most robust design.

Not all statisticians endorse Taguchi's procedures, but

they are widely used. Taguchi is affiliated with the American Suppliers Institute (ASI), Allen Park MI, which has registered the term "Taguchi Methods" as a trademark. Taguchi's book, *Introduction to Quality Engineering: Designing Quality into Products and Processes*, is available from ASI.

Table 3

Test	Temp	Length	L/T Ratio	S/N
1	N	N	N	-3.54
2	L	L	L	-6.70
3	H	L	L	-4.71
4	L	H	L	-3.61
5	H	H	L	-2.45
6	L	L	H	-2.83
7	H	L	H	-2.41
8	L	H	H	-4.18
9	H	H	H	-3.05

Other references are:

1. *Taguchi Techniques for Quality Engineering*, by P.J. Ross, published in 1988 by McGraw-Hill.
2. *Quality Engineering Using Robust Design*, by M. S. Phadke, 1989, Prentice Hall.
3. *Taguchi Methods, A Hands-on Approach*, by G. S. Peace, 1993, Addison-Wesley.

Future Issues:

RAC's Selected Topics in Assurance Related Technologies (START) are intended to get you started in knowledge of a particular subject of immediate interest in reliability, maintainability and quality. Some of our upcoming topics being considered are:

- Commercial Off-the-Shelf Equipment
- Reliability Predictions
- Dormancy
- Mechanical Reliability
- Software Reliability

Please let us know if there are subjects you would like covered in future issues of START.

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